Detection of Delaminations of Laminar Composites by Infrared Thermography

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Abstract
The laminar composite materials may lost their bending stiffness and strength by formation of the delamination during production and service. However, these delaminations can be barely visible by the naked eye and thus the damage detection of composites materials is inspected generally in laboratory. In this study, the in situ detection of the delamination in laminar composite materials was investigated by using infrared thermography approach. First the composite materials were subjected to low velocity impacts to create arbitrary delamination. Then, these composites materials were exposed to cyclic bending loading and observed by using a thermal camera. The temperature variations caused by the friction within delaminated field have been investigated. It is shown that the delamination damages under cyclic loads cause to a serious internal friction and the delamination can be detected by infrared thermography.

Keywords— Infrared thermography, image processing, laminated composites, delamination, cyclic loading.

1 Introduction
The detection of the damage accumulation and crack nucleation in materials has great importance in practical applications [1] since the structural defects generally cannot be detected until they became visible by the naked eye unless any non-destructive tests are applied.

Composite materials have unique damage modes which can form under static, impact or cyclic loading. For example, the laminated composites are susceptible to delamination frequently caused by impact loading during manufacturing, service and maintenance. These damage modes are matrix damage, fiber damage, fiber/matrix debonding and delamination between successive plies. These damage types are generally invisible by naked eye. The above mentioned damage types can result in dramatic decrease in strength, fatigue life and flexural properties such as bending stiffness and bending strength [2]. This situation is very important especially for machine parts working under cyclic loading. So, it is very important to detect whether these type of damages have formed or not. On the other hand, these types of damages generally form while material works in service. Due to size and dimension limitations and transportation difficulties these types of materials are generally not tested in laboratory. So, the damage detection should generally be performed in situ.

In this situation, non destructive testing methods such as acoustic emission, ultrasonic and x-ray can be used. However, these techniques require specimens preparation [3] and not suitable for testing of a machine element while working except for acoustic emission technique. However, acoustic emission technique is
In case of cyclic bending loading, the delaminated field within material creates friction between mating surfaces by the shear motion which leads to the heating of the delaminated field. The heating at the delaminated surfaces results in temperature increase at the surface of the material enabling us to detect delaminated zones within material by using an infrared (IR) camera. Some authors [4-6] reported that defects, fatigue cracks can result in rapid temperature increase. It is also reported that when the material is subjected to external loads, some of the energy applied is converted into heat by the material [7]. Meola and Carlomagno used the infrared thermography (IRT) for determine the response of composite materials under impact loading [8, 9]. They showed that thermal events during impact loading can be visualized by IRT.

IRT is a non contact technique that enables us to capture invisible thermal radiation from stationary or moving objects at any distance and obtain their temperature maps [10, 11]. In this technique, specimen preparation is not needed and no practical limitations on dimensions and shape. So, the IRT perfectly suitable for in-situ damage detection of laminar composites [11]. This technique enables also the user to get recorded data for in-situ and instant damage detection. Nowadays, the developments of IRT have also enabled the scientists to investigate the fatigue of metals by using this technique [12-14].

Active IRT was utilized for impact damage in carbon fiber composites [15-17] and glass-fiber composites [18]. IRT was also utilized for damage detection [19-22] and fracture toughnness evaluation under static or fatigue loading [15, 16, 23, 24].

In this study, the IRT was used for in-situ delaminations detection in laminar composites. Delaminated zones have been created by the application of impact loading at different impact velocities. It is shown that invisible delaminations can be detected by applying cyclic loading while surface temperatures of the materials measured instantly during the working period and the variation of surface temperatures can be determined as an indicator of damage formation.

2 Theory of Heat Generation under Cyclic Loading

It was shown by many authors that the temperature increase in material due to cyclic loading can be divided into three characteristic stages as follows [25],

- Initial thermal gradient,
- Temperature stabilization (steady state),
- Final rapid temperature increase.

Curti et al. [26] also showed that the fatigue limit can be correlated to the initial thermal gradient stage and to the temperature stabilization (steady state) stage [13, 27, 28]. The overall mechanical energy input to the test specimen under cyclic loading can be written as [29],

\[ \int_V \left( \phi \sigma_{ij} \cdot d \varepsilon_{ij} \right) \cdot f \cdot dV \] (1)

where \( V \) is volume of the control, \( \sigma \) and \( \varepsilon \) represents the stress and strain constituents respectively. Here, \( \sigma_{ij} \) is stress tensor, \( \varepsilon_{ij} \) is strain tensor and \( f \) represents the cyclic loading frequency in Hertz. Damage formation in terms of matrix cracking, fiber failure and fiber/matrix interface debonding can affect the stress and strain distribution within material and also affect the heat input expressed in Equation (1). However, the most significant heat input is obtained due to delaminations.

In case of delaminations, it results in friction between mating surfaces under cyclic loading. The dissipated energy due to friction is caused to heat generation and temperature increase. The heat (generation) input due to friction can be expressed as follows.

\[ P = F_{Fr} \cdot V_{avg} \] (2)

Where \( F_{Fr} \) and \( V_{avg} \) represent the friction force and the average relative velocity between the delaminated surfaces, respectively. Since the cycling loading applied as sinusoidal, the relative displacement between adjacent surfaces can be expressed as follows.

\[ \varepsilon(t) = \varepsilon_{max} \cdot \sin(\Omega t) \] (3)

Where \( \varepsilon_{max} \) is maximal displacement between adjacent surfaces at delaminated field and \( \Omega \) is the cyclic loading frequency in rad/sec. Hence the average velocity can be expressed as follows.

\[ V_{avg} = \frac{\Delta \varepsilon}{\Delta t} = \frac{1}{T} \int_0^T |\Omega \cdot \varepsilon_{max} \cdot \cos(\Omega t)| = 4 \cdot \varepsilon_{max} \cdot f \] (4)

Where \( f \) represents the cyclic loading frequency in Hertz. By using above equations the heat generation
rate by friction at delaminations can be expressed as follows.

\[ q^1 = \frac{P}{A_{DZ}} = \frac{4 \varepsilon_{\text{max}} f E \mu}{A_{DZ}} \] (5)

Where \( q \) represents heat flux by means of the frictional heat generation over delaminated zone (ADZ) and \( \mu \) represents friction coefficient between mating surfaces. So, an additional heat generation due to friction between delaminated surfaces can be expressed as following equation.

\[ q = \int_{A_{DZ}} (\mathbf{f} \cdot \mathbf{dV} + \int_{A_{DZ}} (\mathbf{f} \cdot q^1 \cdot dA_{DZ}) \] (6)

The mechanical energy dissipates as heat transfer by conduction, convection and radiation energy while the remaining is dissipated by the variation of the internal energy and stored energy of cold work \((\dot{E}_p)\). So, the global heat equation of a material with delaminations can be expressed as follows.

\[ \int_V (\mathbf{f} \cdot d\mathbf{V}) + \int_{A_{DZ}} (\mathbf{f} \cdot q^1 \cdot dA_{DZ}) = \int_V -\lambda \nabla^2 T \cdot d\mathbf{V} + \int_{S_{CV}} \alpha (T - T_{\infty}) \cdot dS_{CV} + \int_{S_{IR}} \kappa \sigma_n (T^4 - T_{\infty}^4) \cdot dS_{IR} + \int_V (\rho \cdot c_\mathbf{v} \cdot \frac{dT}{dt} + E_p) \cdot d\mathbf{V} \] (7)

The left side of the equation represents the overall energy input during cyclic loading. The first term at right side of the equation is \( \int_V -\lambda \nabla^2 T \cdot d\mathbf{V} \) which represents the heat conduction. Where, \( \lambda \) is thermal conduction coefficient.

The second term is \( \int_{S_{CV}} \alpha (T - T_{\infty}) \cdot dS_{CV} \) which represents the convectional heat transfer. Where, \( \alpha \) is the convection heat transfer coefficient \( S_{CV} \) is the area subjected to convectional heat transfer and \( T_{\infty} \) is ambient temperature.

The third term at right side is \( \int_{S_{IR}} \kappa \sigma_n (T^4 - T_{\infty}^4) \cdot dS_{IR} \) which represents the heat transfer by radiation. Here, \( \sigma_n \) is Stephan-Boltzmann coefficient \( \kappa \) is surface emissivity and \( S_{IR} \) is the area subjected to heat transfer by radiation.

The last term \( \int_V (\rho \cdot c_\mathbf{v} \cdot \frac{dT}{dt} + E_p) \cdot d\mathbf{V} \) consists of two terms.

One is the variation of internal energy and the second is critical energy level. Where, \( \rho \) is density, \( c \) is specific heat of the material and, \( E_p \) is critical energy level at the fracture.

3 Experimental Study

The tested material is 8 plied E-glass/epoxy unidirectional composite plates with fiber volume fraction of 80% (Fig.1.b). The mechanical properties of the constituents and the testing specimens are presented in Tables 1 and 2 respectively. Low velocity impact tests were performed under simply supported boundary condition while the impactor mass is 15 Kg. Therefore, the impact tests were conducted for three different velocities as 1 m/s, 1,25 m/s and 1,5 m/s.

Table 1. Mechanical properties of the reinforcement and the matrix.

<table>
<thead>
<tr>
<th>Reinforcement (E-glass)</th>
<th>E (GPa)</th>
<th>( \sigma_{TS} ) (MPa)</th>
<th>( \rho ) (g/cm(^3))</th>
<th>( \varepsilon_{\text{max}} ) (%)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Epoxy</td>
<td>3.4</td>
<td>50-60</td>
<td>1.2</td>
<td>1.5-2</td>
</tr>
</tbody>
</table>

Table 2. Properties of specimens.

<table>
<thead>
<tr>
<th>Property</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Strength (MPa) (Longitudinal)</td>
<td>632</td>
</tr>
<tr>
<td>Strength (MPa) (Transverse)</td>
<td>68</td>
</tr>
<tr>
<td>Poisson’s ratio</td>
<td>0.19</td>
</tr>
<tr>
<td>Fiber volume fraction (%)</td>
<td>80±0.6</td>
</tr>
<tr>
<td>Longitudinal Elasticity Modulus (MPa)</td>
<td>1040</td>
</tr>
<tr>
<td>Transverse Elasticity Modulus (MPa)</td>
<td>201</td>
</tr>
</tbody>
</table>

The test specimens were first subjected to low velocity impacts by 15 kg under impact velocity of 1 m/s, 1,25 m/s and 1,5 m/s which create 7,5 Joule, 11,7 Joule and 16,8 Joule respectively. Then, the one end of the test specimen is clamped and the other end is moved by an adjustable crank which is driven by an electrical engine running at 25 cycle/sec. The test stand is shown in Fig.1.a. The end displacement \((\delta)\) of the test specimen can be adjusted by crank rig. So, the cyclic loads were applied as ±4 mm, ±5 mm and ±6 mm end displacements respectively. The experimental setup of the IRT used to obtain thermal images is shown in Fig.2. The properties of FLIR E45 IR camera used in study are presented in Table 3.
Figure 1. a) Schematic drawing of measuring system b) test specimen.

Figure 2. The experimental setup of the IRT.

Table 3. Properties of FLIR E45 IR camera.

<table>
<thead>
<tr>
<th>Detector Type</th>
<th>Focal Plane Array (FPA), Uncooled Microbolometer 160x120 Pixels</th>
</tr>
</thead>
<tbody>
<tr>
<td>Spectral Range</td>
<td>7.5 to 13 μm</td>
</tr>
<tr>
<td>Temp. Range</td>
<td>-20 °C to +250 °C</td>
</tr>
<tr>
<td>Thermal Sens.</td>
<td>0.1 °C at 30 °C</td>
</tr>
<tr>
<td>Video Output</td>
<td>Standard RCA Composite Video</td>
</tr>
<tr>
<td>Image Freq.</td>
<td>50/60 Hz</td>
</tr>
<tr>
<td>FOV / Min.</td>
<td>Typical 34°x25°/0.1m (with 9.2 mm lens)</td>
</tr>
</tbody>
</table>

During cyclic bending loading test, the thermal images were obtained by FLIR E45 IR camera for 30 minutes under different loading levels (see Fig.1). Meanwhile, the thermal images of the composite material were recorded at sampling rate of 30 frames per second (33 ms interval). Primarily, to both reduce the data to be processed and shorten the processing time, the delamination field which will be examined is determined at the each thermal image as shown in Fig.3. Then, the temperature values of the impact center and the temperature distributions of the delamination field are obtained by applying the method suggested M. Selek et al [13] to thermal image of this field. Starting from the highest temperature value obtained in the experiments, the contour images of the delamination field were obtained from its temperature distribution at intervals of 1 °C. These processes are showed in Fig.3.

Figure 3. The thermal and contour images of the impact center and the delamination field.

4 Results

The visible damage formation of test specimens is shown in Fig.4. As seen in this figure, when the specimens subjected to impact loading, visible and invisible damage can form. However, that delamination is generally invisible. After the impact loading, the specimens were fixed at bending fatigue test stand and tested under different cyclic loads. The impact loading can create matrix cracks and delamination in the specimen. Due to the formation of these damages, the internal friction localize on that regions especially mating surfaces of delaminated fields. This situation creates considerable amount of the internal friction under cyclic loading which can be observed as temperature increase. So, these regions are expected to be seen in higher temperatures in comparison with undamaged regions. Since the test materials have been previously subjected to impact loading, while under bending fatigue, only the impacted region has been observed by IR camera as shown in Fig.3.
Figure 4. The visible images of the damage formations after impacts of various velocities.

Fig. 5-7 show the temperature variations of impact center versus time.

Figure 5. Temperature variations of impacted specimens with different impact velocities under fatigue loading of ±4mm displacement.

As seen in these figures, the temperature values start to increase from ambient temperature and after some time, it remains constant which indicates thermal equilibrium. It is seen in these figures that the intact specimens show the lowest temperatures. As the impact velocity increases, the impact energy results in formation of larger delaminations. The larger delaminated fields create higher friction between the mating surfaces. So higher temperatures are obtained at specimens that impacted by higher velocities. It is also seen in Fig. 5-7, the increase of the cyclic loads increases also the temperature in delaminated field. However, general trend of temperature variation versus time is same for all specimens.

Figure 7. Temperature variations of impacted specimens with different impact velocities under fatigue loading of ±6mm displacement.

Fig. 8 shows the surface temperature variations of previously impacted specimens tested at ±4 mm displacement. As seen in this figure, the surface temperatures of the specimens increase with time. Specimens impacted at 1 m/s have not showed considerable temperature increase. However, specimens impacted at 1.25 m/s and 1.5 m/s showed notable temperature increase. On the other hand, the specimens impacted at 1.5 m/s velocity showed the highest temperature increase. Consequently as the impact velocity increases the delaminated field increases too. Eventually more internal friction occurs and consequently higher temperatures were obtained.

Fig. 9 shows the surface temperature variations of previously impacted specimens tested at ±5 mm displacement. The obtained temperature variations for ±5 mm displacement and temperature variations for ±4 mm displacement are similar. However, the edge effect becomes important when the end displacement increases. Especially the regions close to clamping are subjected to high stress levels. So, for an intact specimen, it is expected to observe relatively high temperatures near the clamped region as seen in the Fig. 9.

Fig. 10 shows the variation of surface temperatures of specimens subjected to cyclic loading at ±6 mm dis-
placement and different impact velocities. This case is similar to the previous cases. In addition, high displacement has led to high stress level at the region near clamping and yielded the highest surface temperature.

Figure 8. Thermal images of impacted specimens with different impact velocities under fatigue loading of ±4mm displacement.

Figure 9. Thermal images of impacted specimens with different impact velocities under fatigue loading of ±5mm displacement.

After the test, the test specimens have been checked against damage progression and no considerable expansion of delamination has been observed.
field must be far enough from clamped regions of the specimens. Otherwise, heat generation can arise near clamped regions and affects the temperature distribution formed by internal friction of damaged field. This situation can result in misinterpretation. In this case, in order to designate the sufficient end displacement that will not increase the present damage but, will create considerably heat is depending on the stress intensity of the damage field and material’s interlaminar fracture toughness and specimen’s geometry.

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7 References


